

Design and Analysis of Cyber-Physical Systems: AADL and Avionics Systems

Software Engineering Institute
Carnegie Mellon University
Pittsburgh, PA 15213

Peter H. Feiler
May 1, 2013



Copyright 2013

Carnegie Mellon University and IEEE

This material is based upon work funded and supported by the Department of Defense under Contract No. FA8721-05-C-0003 with Carnegie Mellon University for the operation of the Software Engineering Institute, a federally funded research and development center.

NO WARRANTY. THIS CARNEGIE MELLON UNIVERSITY AND SOFTWARE ENGINEERING INSTITUTE MATERIAL IS FURNISHED ON AN "AS-IS" BASIS. CARNEGIE MELLON UNIVERSITY MAKES NO WARRANTIES OF ANY KIND, EITHER EXPRESSED OR IMPLIED, AS TO ANY MATTER INCLUDING, BUT NOT LIMITED TO, WARRANTY OF FITNESS FOR PURPOSE OR MERCHANTABILITY, EXCLUSIVITY, OR RESULTS OBTAINED FROM USE OF THE MATERIAL. CARNEGIE MELLON UNIVERSITY DOES NOT MAKE ANY WARRANTY OF ANY KIND WITH RESPECT TO FREEDOM FROM PATENT, TRADEMARK, OR COPYRIGHT INFRINGEMENT.

This material has been approved for public release and unlimited distribution.

This material may be reproduced in its entirety, without modification, and freely distributed in written or electronic form without requesting formal permission. Permission is required for any other use. Requests for permission should be directed to the Software Engineering Institute at permission@sei.cmu.edu.

DM-0000251



Outline

▶ Software-induced Challenges in Cyber-Physical Systems
SAE AADL: an Architecture Modeling and Analysis Framework
Virtual Integration of an Avionics System
Architectural Fault Modeling of Safety-critical Systems
Conclusions



We Rely on Software for Safe Aircraft Operation

Quantas Landing

Written by htbw
From: soyawan



Even with the autopilot off, flight control computers still `` command control surfaces to protect the aircraft from unsafe conditions such as a stall," the investigators said.

The unit continued to send false stall and speed warnings to the aircraft's primary computer and about 2 minutes after the initial fault `` generated very high, random and incorrect values for the aircraft's angle of attack."

mayday call when it suddenly changed altitude during a flight from Singapore to Perth, Qantas said.

Embedded software systems introduce a new class of problems not addressed by traditional system modeling & analysis

plunge

Autopilot Off

A `` preliminary analysis" of the Qantas plunge showed the error occurred in one of the jet's three air data inertial reference units, which caused the autopilot to disconnect, the ATSB said in a statement on its Web site.

The crew flew the aircraft manually to the end of the flight, except for a period of a few seconds, the bureau said.

Even with the autopilot off, flight control computers still `` command control surfaces to protect the aircraft from unsafe conditions such as a stall," the investigators said.

The unit continued to send false stall and speed warnings to the aircraft's primary computer and about 2 minutes after the initial fault `` generated very high, random and incorrect values for the aircraft's angle of attack."

The flight control computer then commanded a `` nose-down aircraft movement, which resulted in the aircraft pitching down to a maximum of about 8.5 degrees," it said.

No `` Similar Event'

`` Airbus has advised that it is not aware of any similar event over the many years of operation of the Airbus," the bureau added, saying it will continue investigating.

Let's flight switched on the autopilot and generated false data, causing the jet to nosedive.

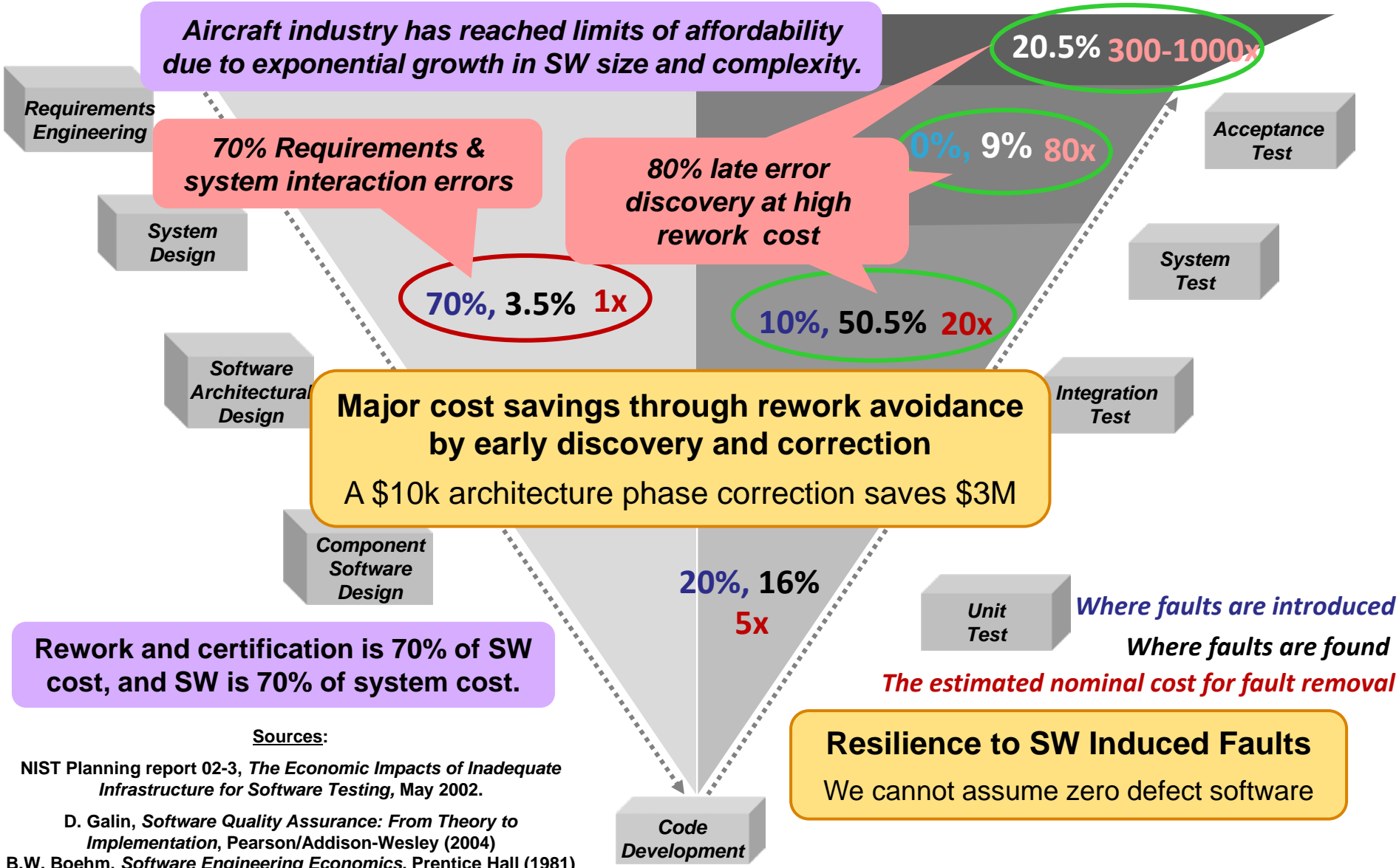
was cruising at 37,000 feet (11,277 meters) when the computer fed incorrect information to the flight control system, the **Australian Transport Safety Bureau** said yesterday. The aircraft dropped 650 feet within seconds, slamming passengers and crew into the cabin ceiling, before the pilots regained control.

`` This appears to be a unique event," the bureau said, adding that

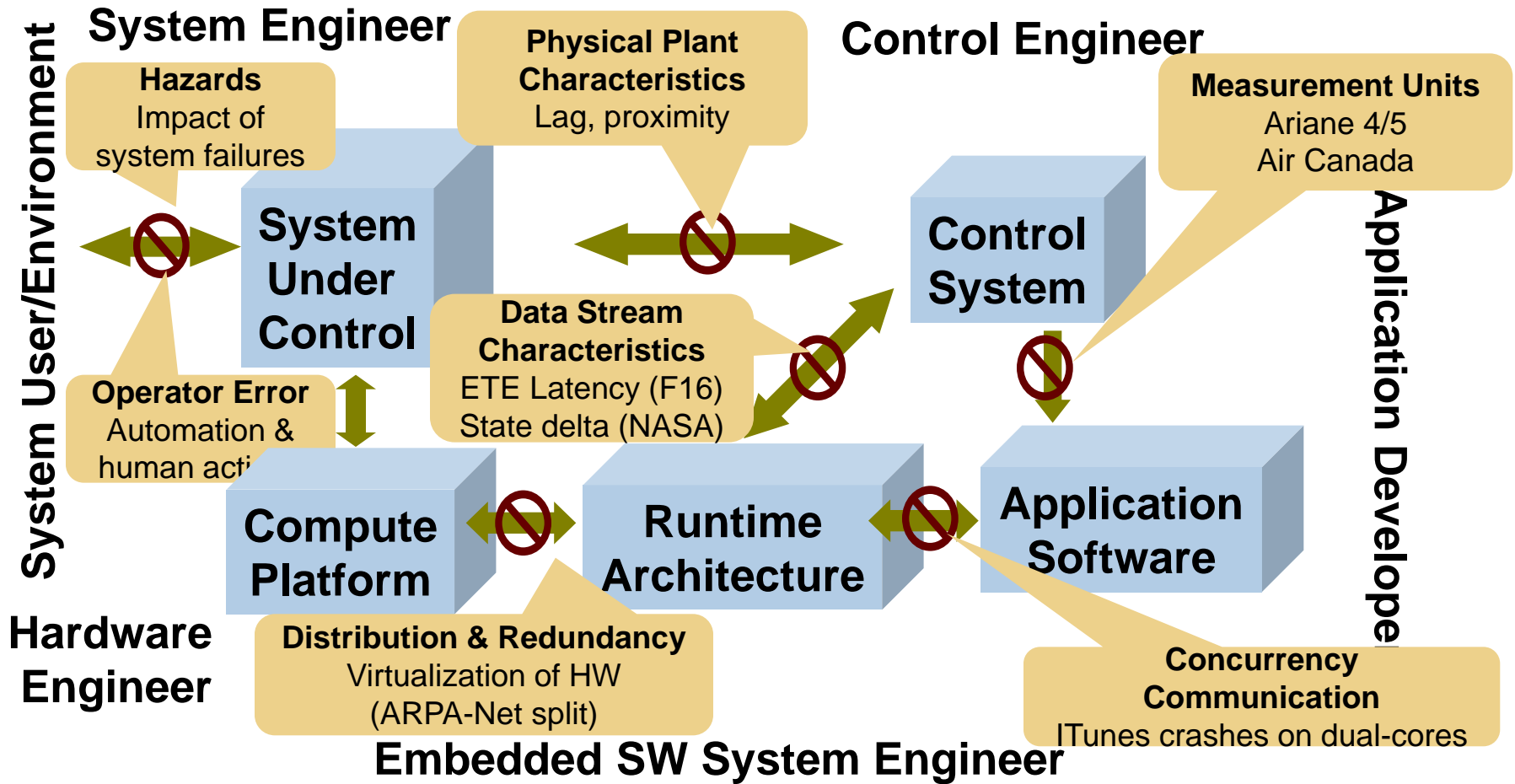
fitted with the same air-data computer. The advisory is `` aimed at minimizing the risk in the unlikely event of a similar occurrence."



High Fault Leakage Drives Major Increase in Rework Cost



Mismatched Assumptions in Embedded SW



Why do system level failures still occur despite fault tolerance techniques being deployed in systems?

SysML does not address Embedded Software System Architecture Issues



Outline

Software-induced Challenges in Cyber-Physical Systems

▶ SAE AADL: an Architecture Modeling and Analysis Framework

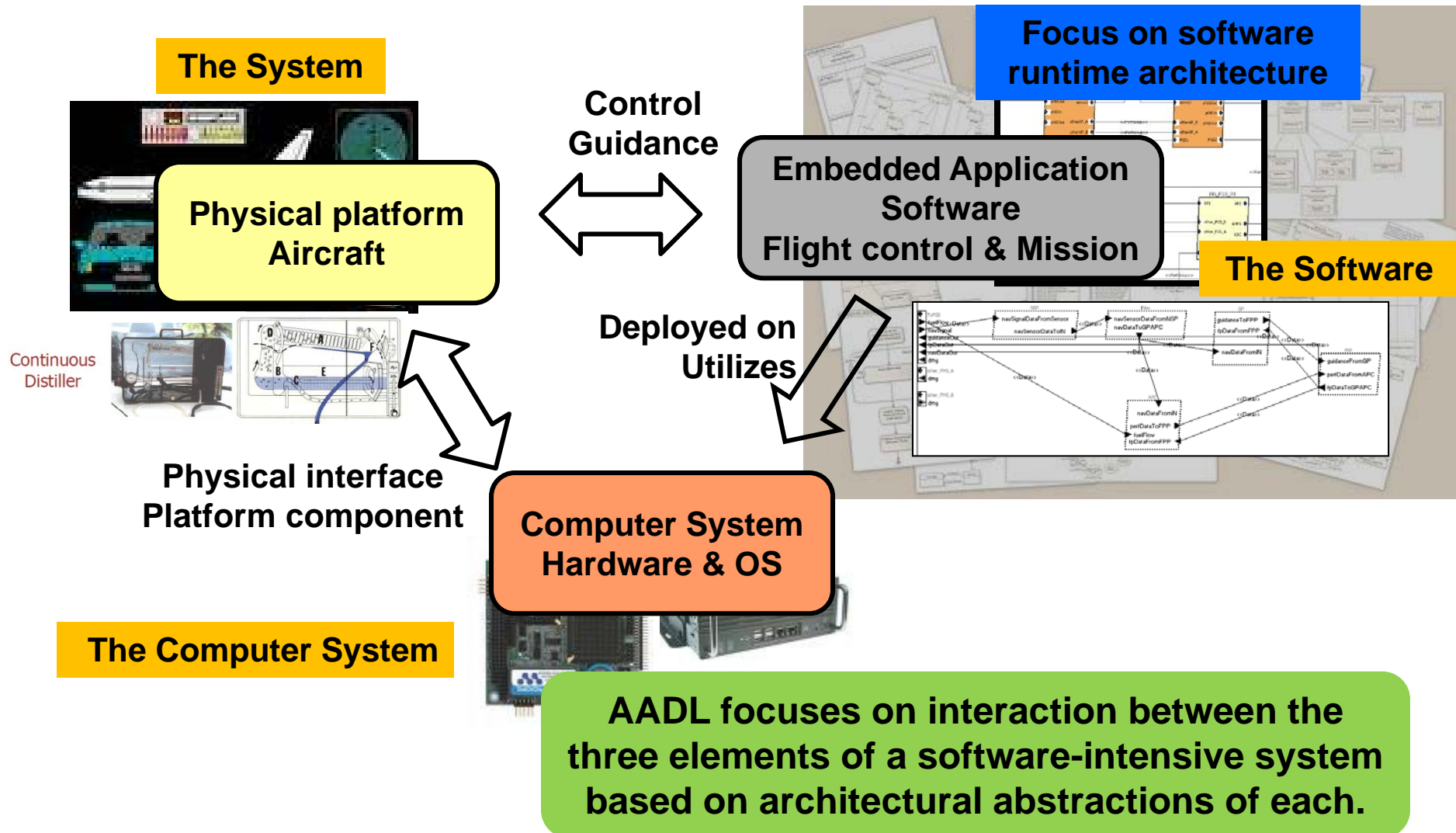
Virtual Integration of an Avionics System

Architectural Fault Modeling of Safety-critical Systems

Conclusions



SAE Architecture Analysis & Design Language (AADL) Standard for Software-reliant Systems



System Level Fault Root Causes

Violation of data stream assumptions

- Stream miss rates, Mismatched data representation, Latency jitter & age

End-to-end latency analysis
Port connection consistency

Partitions as Isolation Regions

- Space, time, and bandwidth partitioning
- Isolation not guaranteed due to undocumented resource sharing
- fault containment, security levels, safety levels, distribution

Process and virtual processor to model partitioned architectures

Virtualization of time & resources

- Logical vs. physical redundancy
- Time stamping of data & asynchronous systems

Virtual processors & buses
Multiple time domains

Inconsistent System States & Interactions

- Modal systems with modal components
- Concurrency & redundancy management
- Application level interaction protocols

Operational and failure modes
Interaction behavior specification
Dynamic reconfiguration
Fault detection, isolation, recovery

Performance impedance mismatches

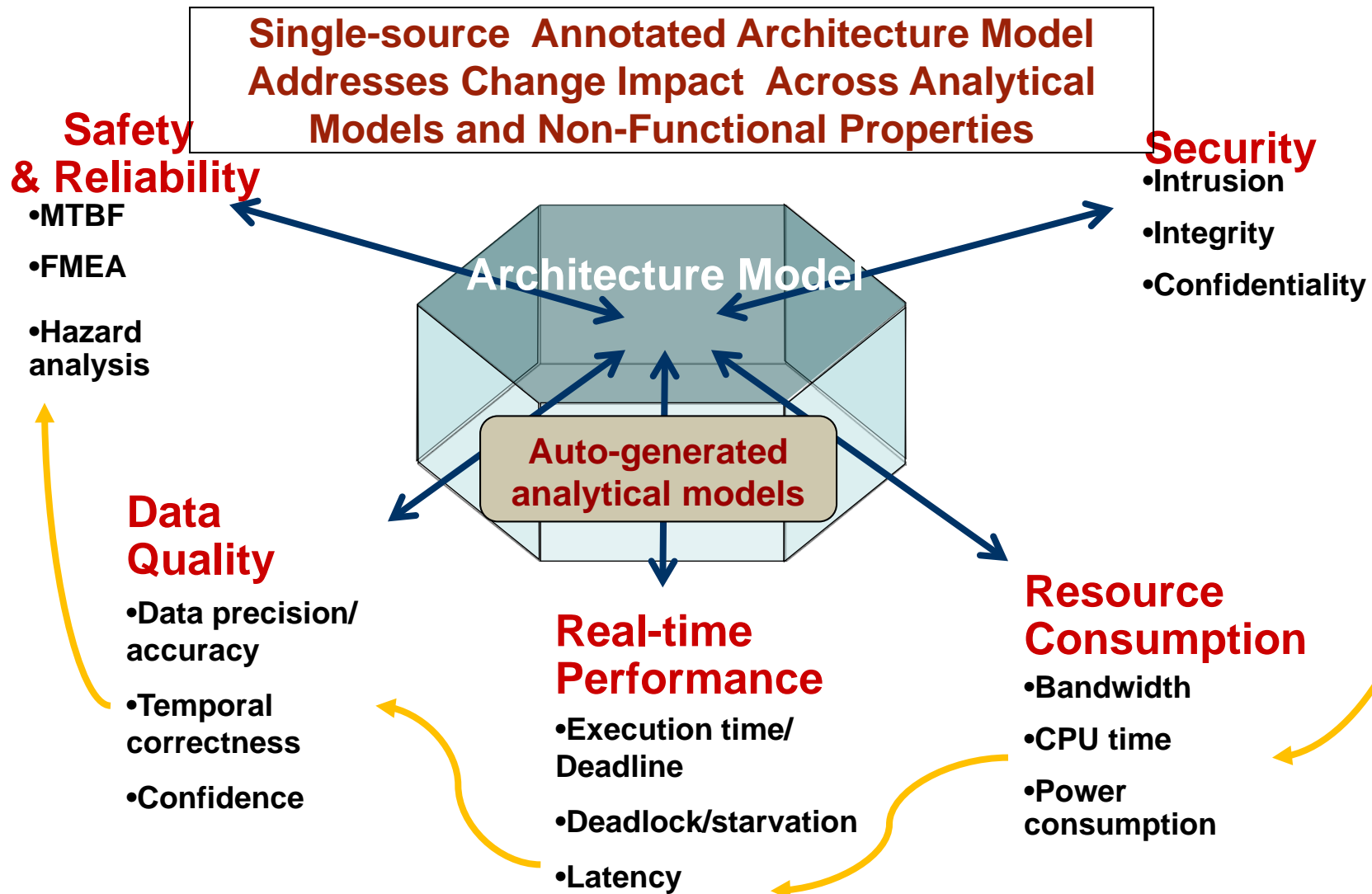
- Processor, memory & network resources
- Compositional & replacement performance mismatches
- Unmanaged computer system resources

Resource allocation & deployment configurations
Resource budget analysis & scheduling analysis

Codified in Virtual Upgrade Validation method



Architecture-Centric Modeling Approach



Outline

Software-induced Challenges in Cyber-Physical Systems

SAE AADL: an Architecture Modeling and Analysis Framework

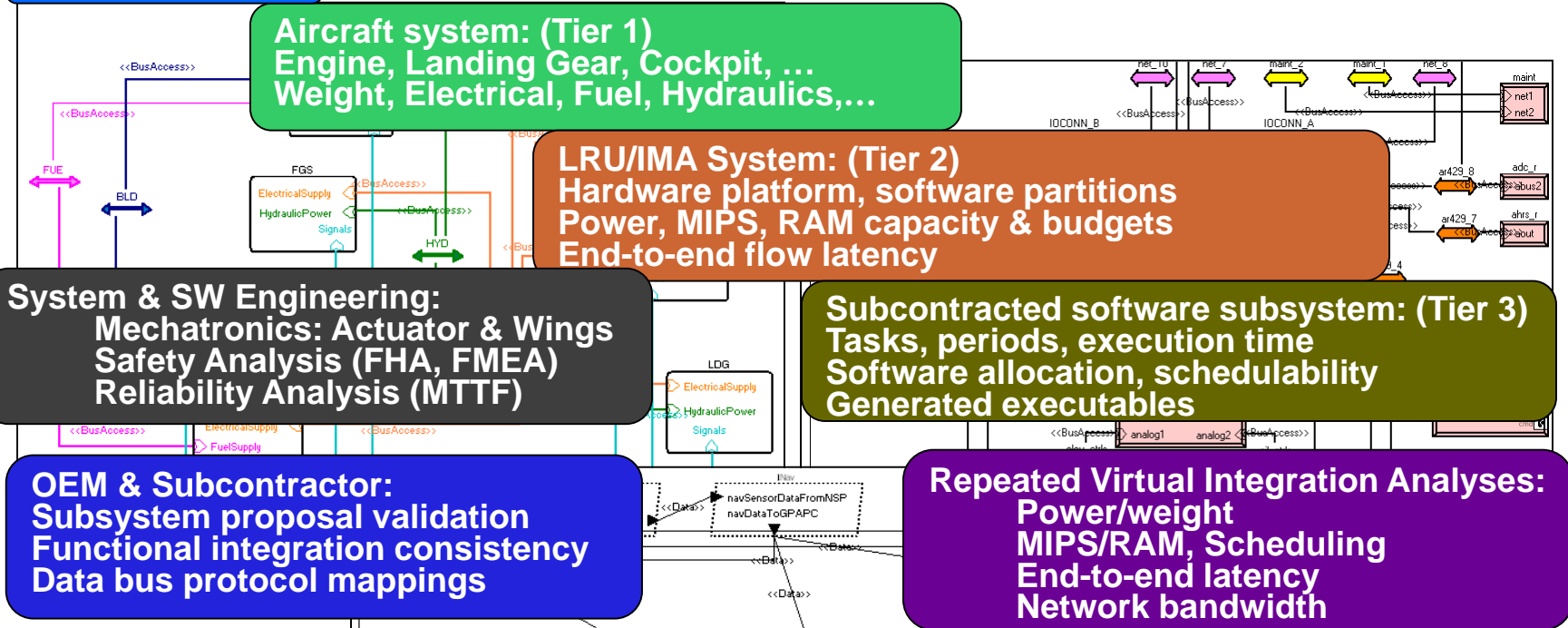
▶ Virtual Integration of an Avionics System

Architectural Fault Modeling of Safety-critical Systems

Conclusions



Early Discovery and Incremental V&V through Virtual Integration (SAVI)



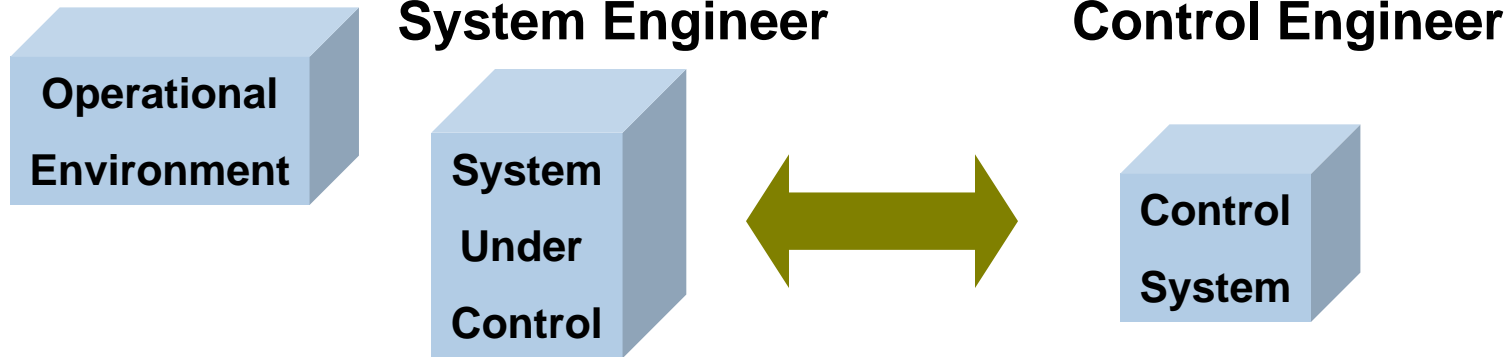
Proof of Concept Demonstration and Transition by Aerospace industry initiative

- Propagate requirements and constraints
- Higher level model down to suppliers' lower level models
- Verification of lower level models satisfies higher level requirements and constraints

- Multi-tier system & software architecture (in AADL)
- Incremental end-to-end validation of system properties



End-to-end Latency in Control Systems



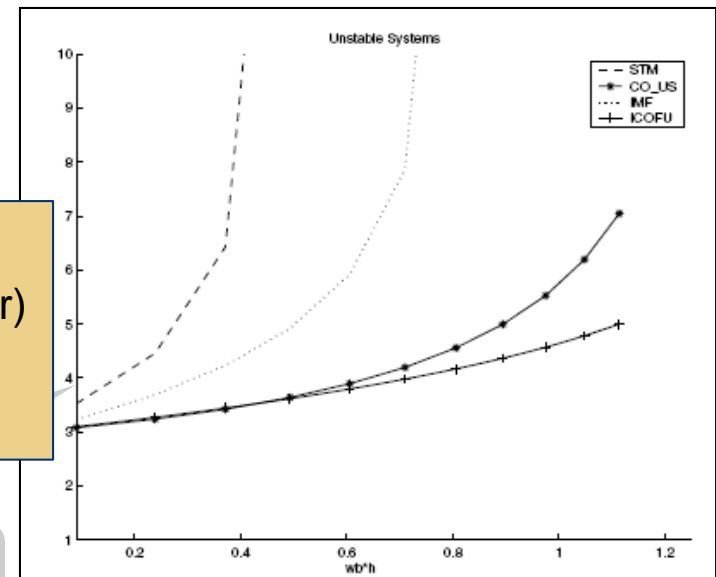
- Processing latency
- Sampling latency
- Physical signal latency

Impact of Software Implemented Tasks

Jitter affects stability of control behavior (subtle value error)
AADL immediate & delayed connections specify deterministic sampling

Impact of Scheduler Choice on Controller Stability

A. Cervin, Lund U., CCACSD 2006



Software-Based Latency Contributors

Execution time variation: algorithm, use of cache

Processor speed

Resource contention

Preemption

Legacy & shared variable communication

Rate group optimization

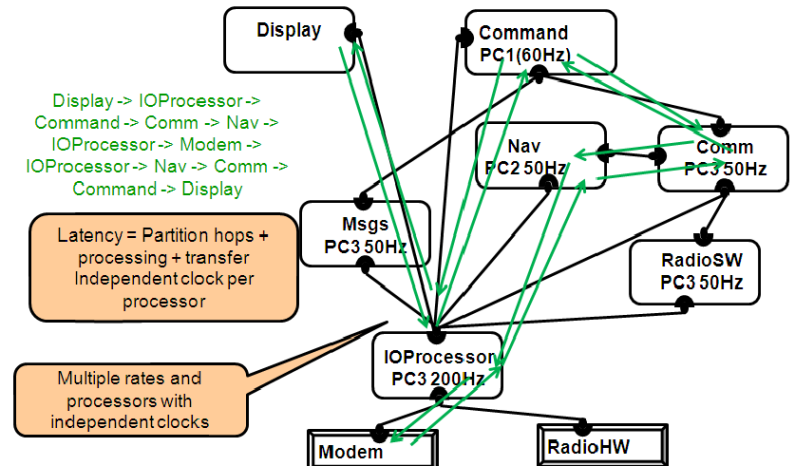
Protocol specific communication delay

Partitioned architecture

Migration of functionality

Fault tolerance strategy

Flow Use Scenario through Subsystem Architecture



Outline

Software-induced Challenges in Cyber-Physical Systems

SAE AADL: an Architecture Modeling and Analysis Framework

Virtual Integration of an Avionics System

▶ Architectural Fault Modeling of Safety-critical Systems

Conclusions



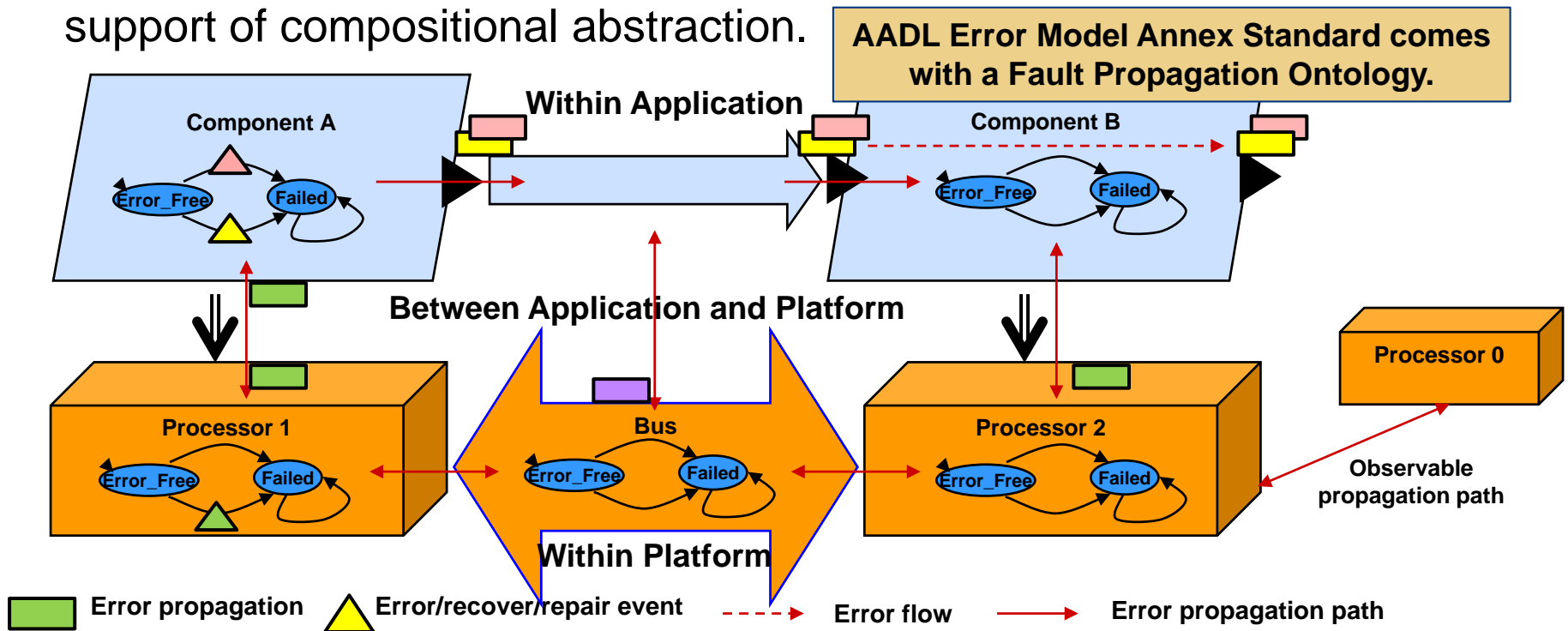
Error Model and the Architecture

Propagation of errors of different types from error sources along propagation paths between architecture components.

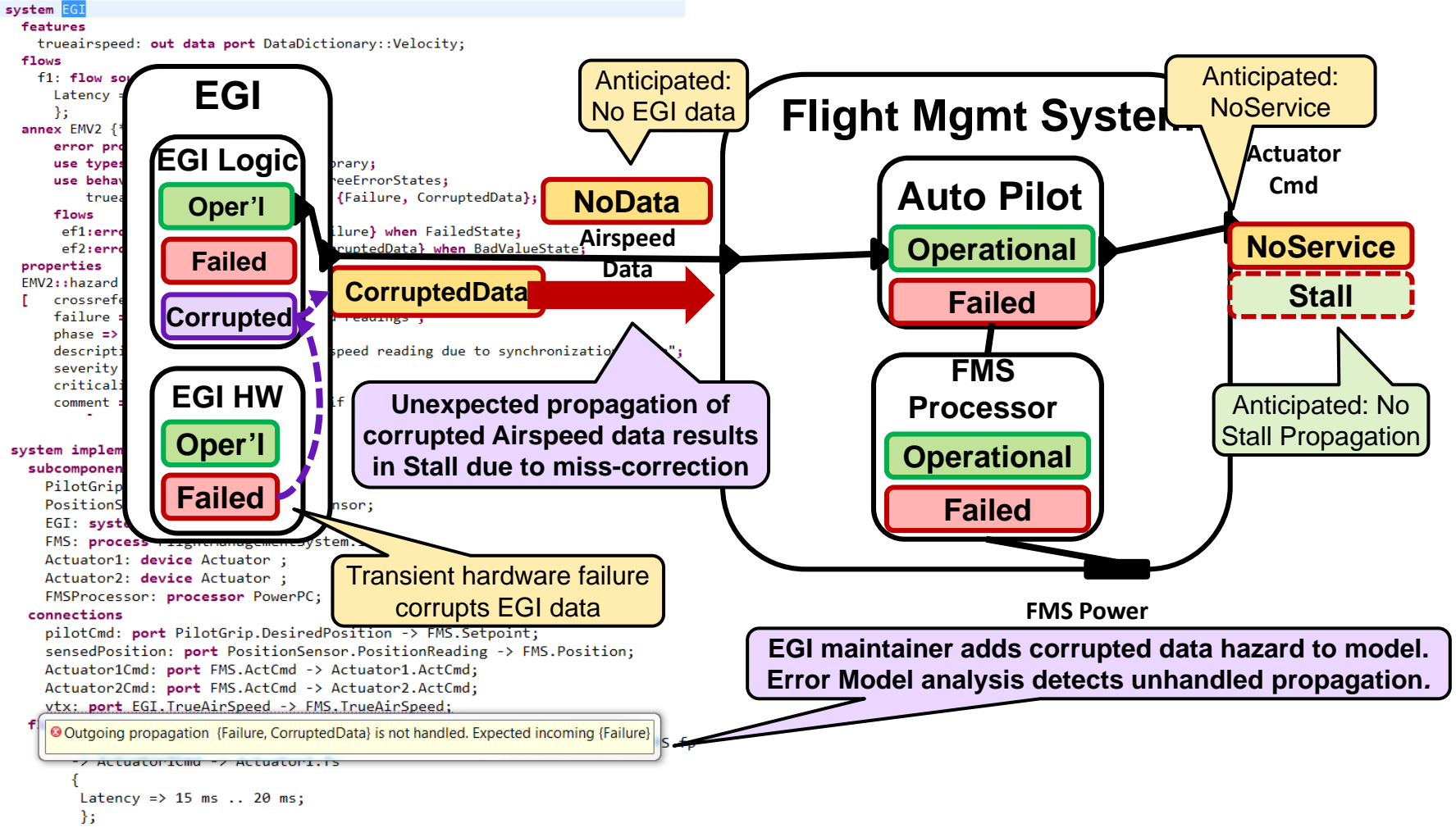
Error flows as abstractions of propagation through components.

Component error behavior as transitions, out propagations, and detection based on event, state and incoming propagation conditions.

Composite error behavior in terms of component error behavior states in support of compositional abstraction.



Discovery of Unexpected PSSA Hazard through Virtual Integration



Recent Automated FMEA Experience

Failure Modes and Effects Analyses are rigorous and comprehensive reliability and safety design evaluations

- Required by industry standards and Government policies
- When performed manually are usually done once due to cost and schedule
- If automated allows for
 - multiple iterations from conceptual to detailed design
 - Tradeoff studies and evaluation of alternatives
 - Early identification of potential problems

ID	Item	Initial State	Initial Failure Mode	1st Level Effect	Transition	2nd Level Effect	Transition	3rd Level Effect	Severity	M
1	Sat_Bus	Working	Failure	Failed		Failed	Recovery	Working		Workin
1	Sat_Payload	Working		Working	Bus failure causes payload transition	Standby		Standby	Bus Recovery Causes Payload Transition	Workin
2	Sat_Bus	Working		Working		Working	5			
2	Sat_Payload	Working	Failure	Failed	Recovery	Working	5			

Largest analysis of satellite to date consists of 26,000 failure modes

- Includes detailed model of satellite bus
- 20 states perform failure mode
- Longest failure mode sequences have 25 transitions (i.e., 25 effects)

Myron Hecht, Aerospace Corp.
Safety Analysis for JPL, member of DO-178C committee



Impact of Deployment Configuration Changes on Availability

FMS Failure on 2 or 3 processor configuration (CPU failure rate = 10^{-5})

FMS Failure Rate	0	$5 \cdot 10^{-6}$	$5 \cdot 10^{-5}$
MTTF – One CPU operational	112,000	67,000	14,000
MTTF – Two CPU operational	48,000	31,000	7,000

Side effects of design and deployment decisions on availability predictions

Workload balancing of partitions later in development affects reliability

3 processor configuration can be less reliable than 2 processor configuration

Example: Replicated AP and FG channel (re)distributed across two processors



Outline

Software-induced Challenges in Cyber-Physical Systems

SAE AADL: an Architecture Modeling and Analysis Framework

Virtual Integration of an Avionics System

Architectural Fault Modeling of Safety-critical Systems

▶ Conclusions



Virtual Upgrade Validation Method

Early discovery of technical risks

Capture Embedded Software System Architecture
Software runtime, computer hardware, mechanical system architecture in same SAE AADL model

Utilize knowledge of potential mismatched assumptions
Codified in Virtual Upgrade Validation method

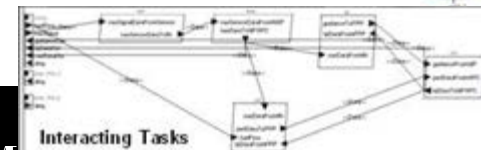
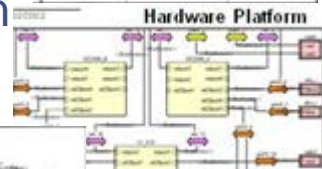
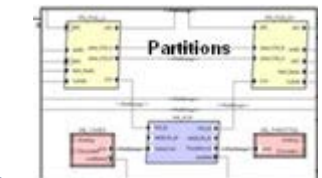
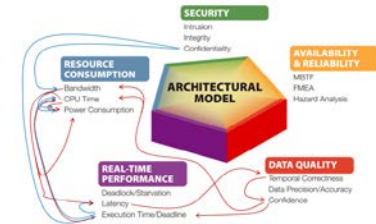
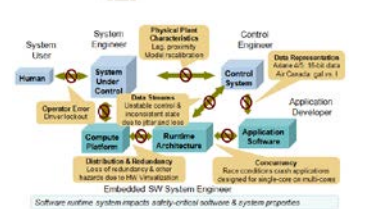
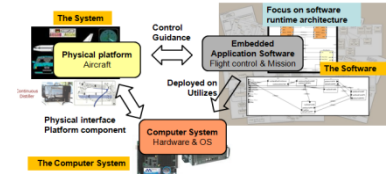
Analyze multiple operational quality attributes
Utilize SAE AADL single model truth approach and well defined semantics

Sample Findings

Potential inconsistency and lack of integrity of recorded aircraft health data

Ambiguous task and communication architecture has priority inversion potential under fault conditions

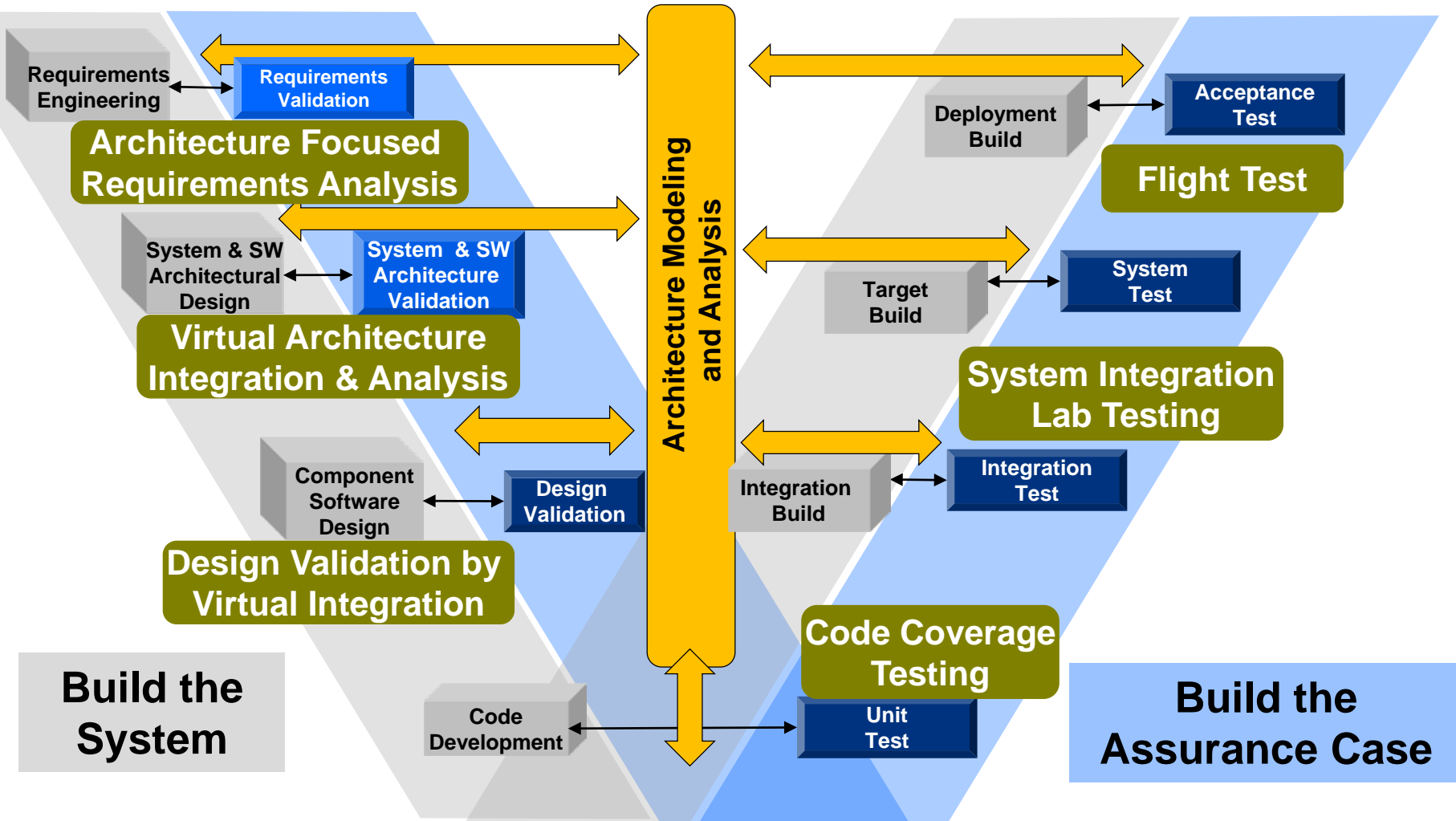
Corrupted airspeed data not considered as hazard



Models



Increased Confidence through End-to-end Virtual Integration and Testing Evidence



Resources

Website www.aadl.info

Public Wiki <https://wiki.sei.cmu.edu/aadl>

AADL Book in SEI Series of Addison-Wesley

<http://www.informit.com/store/product.aspx?isbn=0321888944>

